

DESTECs



A Rigorous Approach to the Design of Cyber-Physical Systems through Co-Simulation

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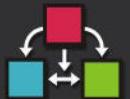
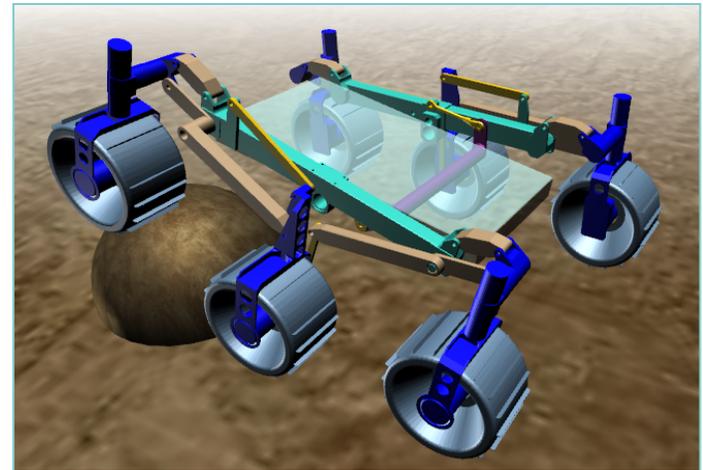
Overview

- Our view of cyber-physical systems
- DESTECS concepts
- Personal transporter case study
- Error and recovery patterns
- Conclusions and future work



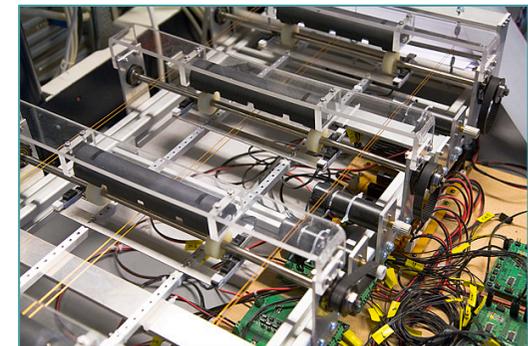
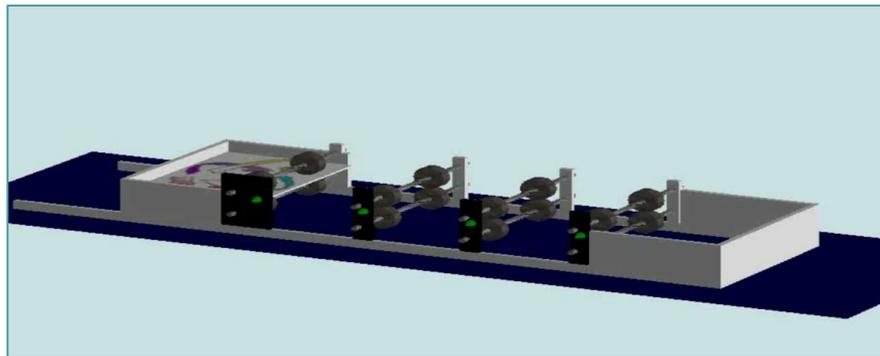
Cyber-physical Systems (1)

- Systems of interacting systems
 - Computing elements
 - Physical elements
 - Human interactions
- Complex, networked character
- Distributed control
- Error detection and recovery



Cyber-physical Systems (2)

- Requires collaborative development
- Analysis of models from different disciplines
 - Diverse cultures, abstractions, formalisms
- Typically tackled separately
- Require early allocation of responsibility to cyber and physical elements
- Need for **design space exploration**



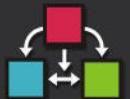
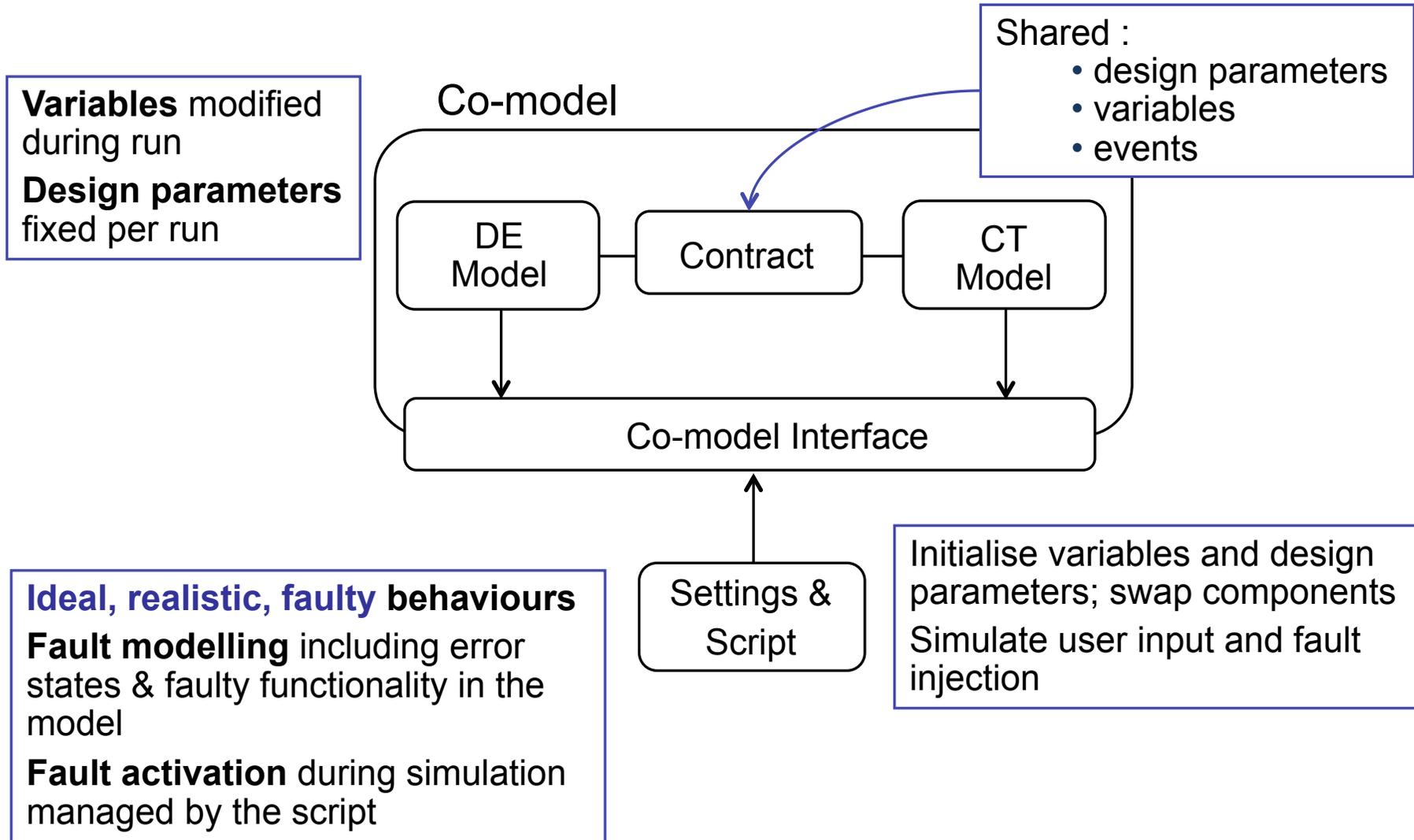
DESTTECS Approach

(www.destecs.org)

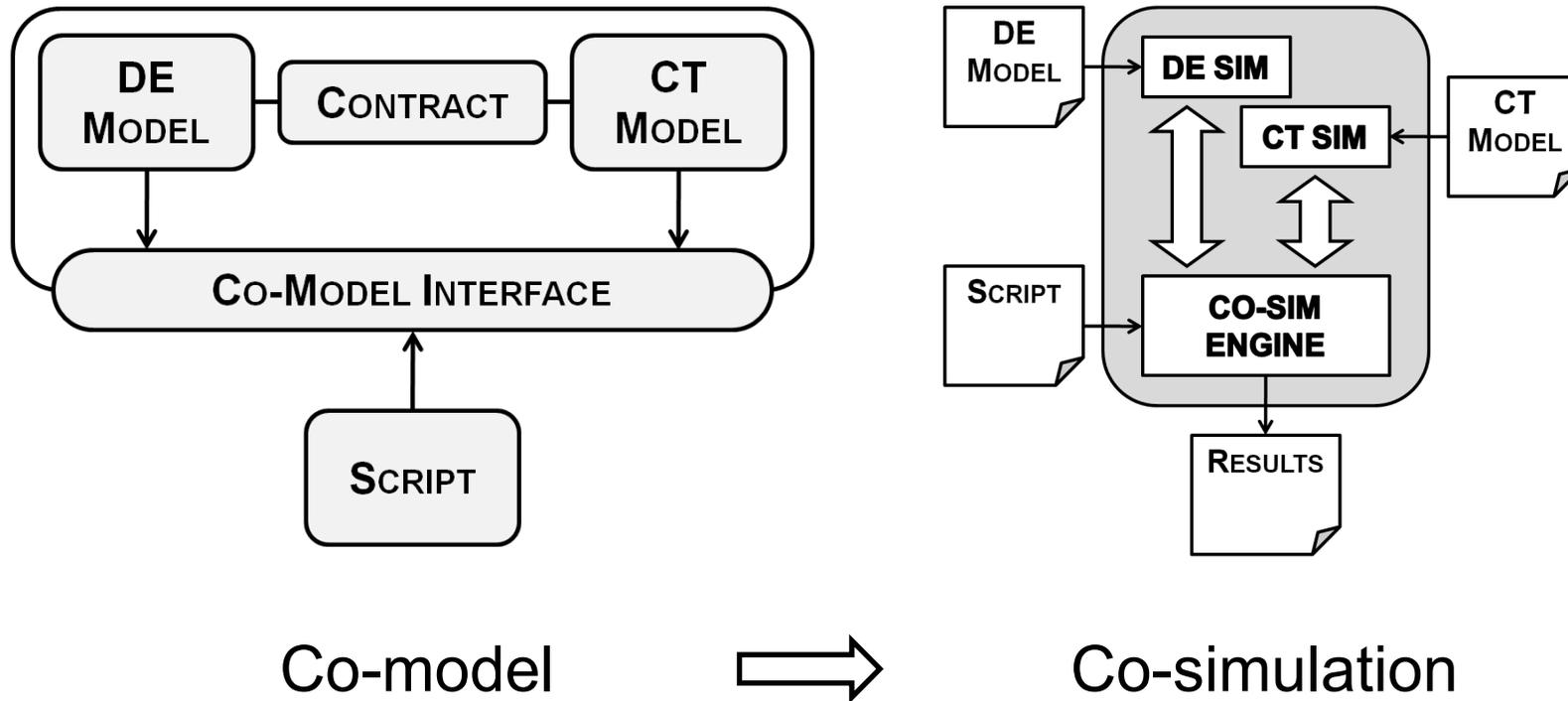
- Bridge gap between disciplines
 - Through co-simulation
 - Combine DE controller models and CT plant models
 - Collaboration while working with familiar formalism
- Developed a tool
- Developed methodological guidelines, incl. patterns
- Model failures, error detection and recovery
- Industrial partners and follow group



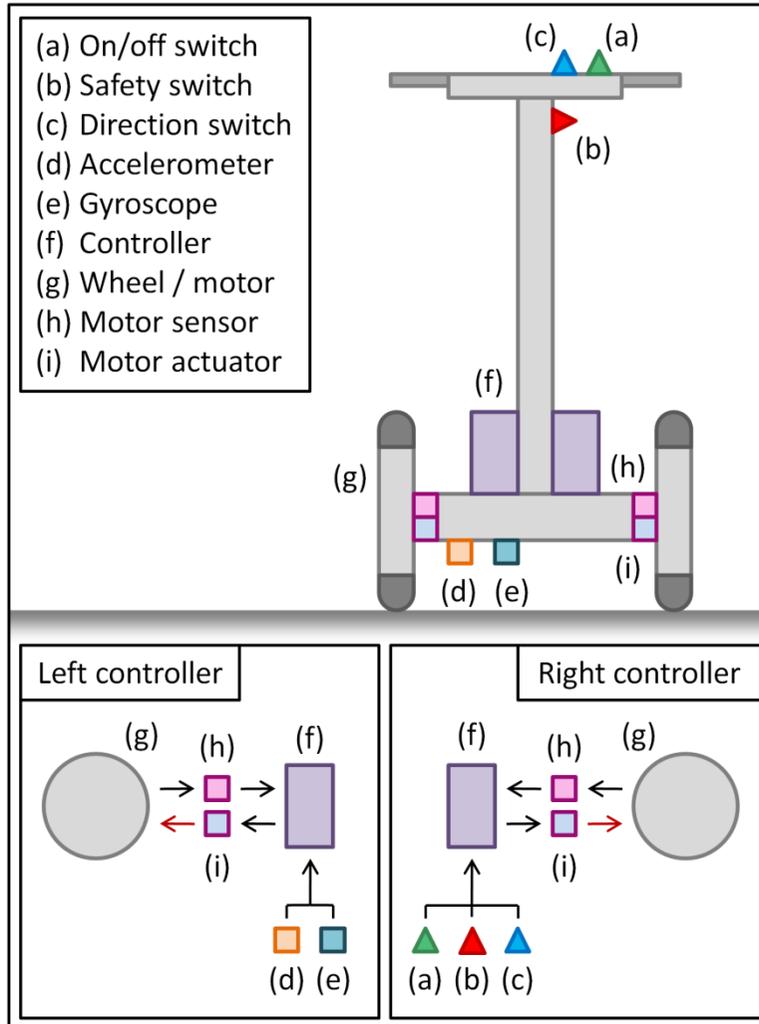
Basic Concepts



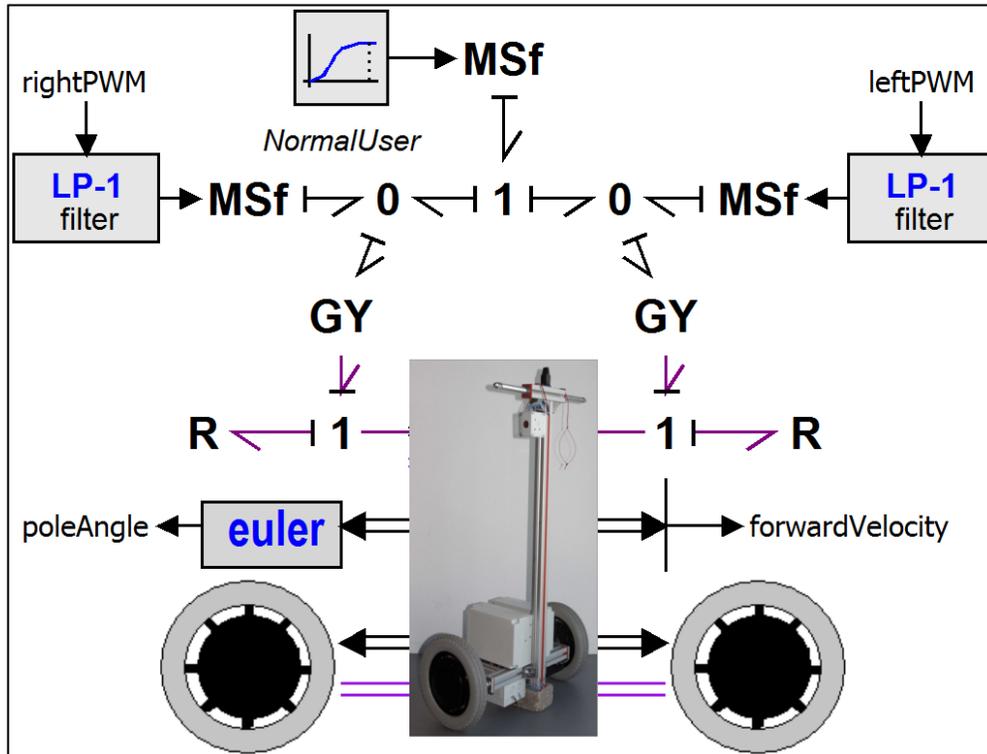
Tool Concepts



Example: Personal Transporter



Personal Transporter (2)



	Name	Type	Notes
controlled	leftPWM	real	range: [-1,1]
	rightPWM	real	range: [-1,1]
monitored	poleAngle	real	range: [0,2 π]
	forwardVelocity	real	

```
class Controller
```

```
instance variables
```

```
-- sensors
```

```
private angle: real;
```

```
private velocity: real;
```

```
-- actuators
```

```
private acc_out: real;
```

```
private vel_out: real;
```

```
-- PID controllers
```

```
private pid1: PID;
```

```
private pid2: PID;
```

```
operations
```

```
public Step : () ==> ()
```

```
Step() == duration(20) (
```

```
  dcl err: real := velocity - angle;
```

```
  vel_out.Write(pid2.Out(err));
```

```
  acc_out.Write(pid1.Out(angle));
```

```
);
```

```
public GoSafe : () ==> ()
```

```
GoSafe() == (
```

```
  vel_out.Write(0);
```

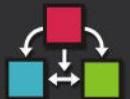
```
  acc_out.Write(0);
```

```
);
```

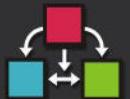
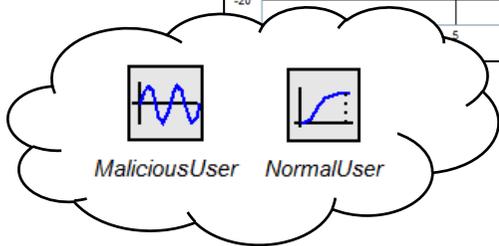
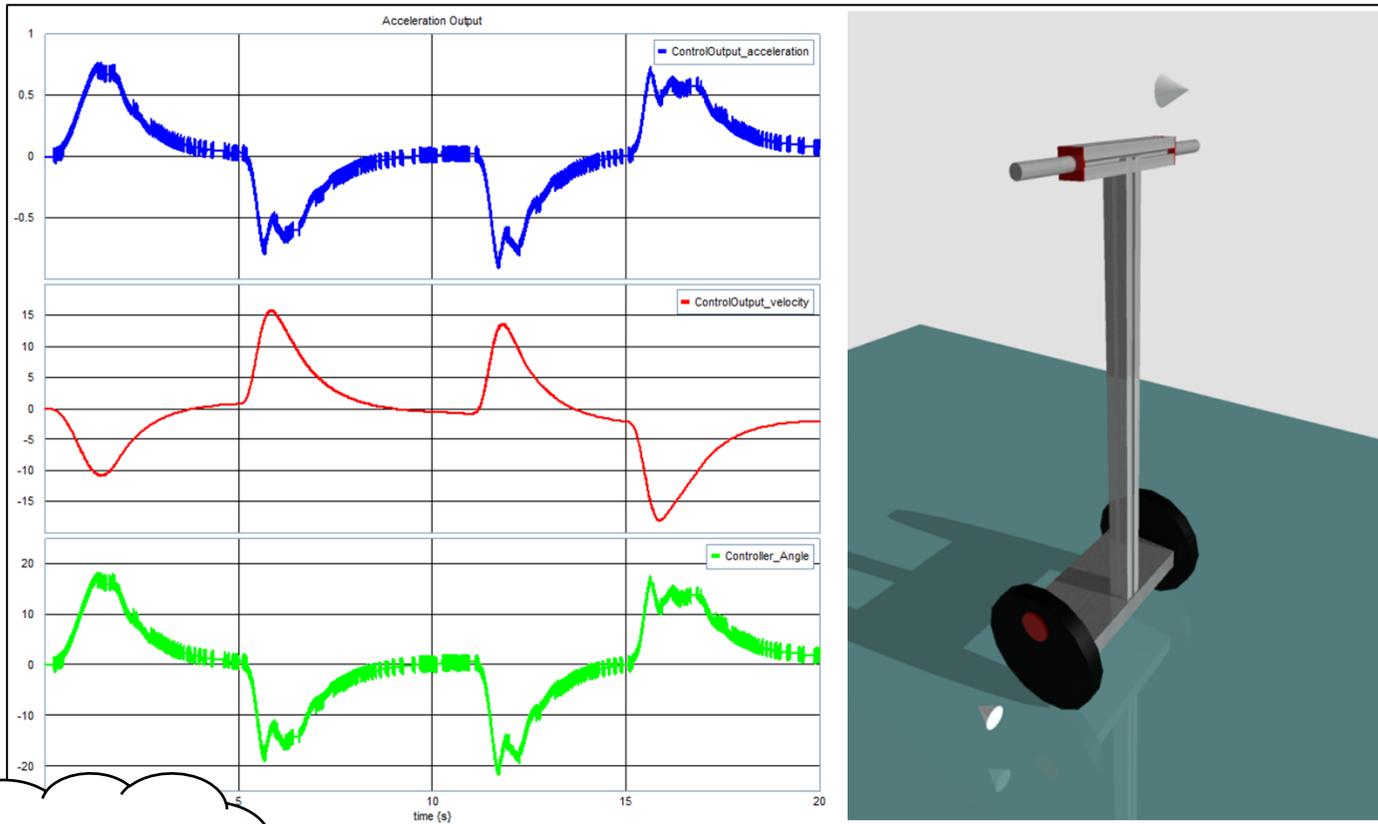
```
thread
```

```
  periodic(1E6,0,0,0)(Step); -- 1kHz
```

```
end Controller
```



Personal Transporter (3)



DESTECs

What is a Pattern?

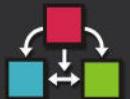
- “Each pattern describes a problem, ... then describes the core of the solution” [AIS77]
- Applied to
 - architecture [AIS77]
 - object-oriented software [GHJV95]
- Includes: name, motivation, solution, related patterns

[GHJV95] Erich Gamma, Richard Helm, Ralph Johnson, and John Vlissides. *Design Patterns: Elements of Reusable Object-Oriented Software*. Addison-Wesley, 1995.

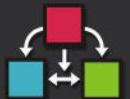
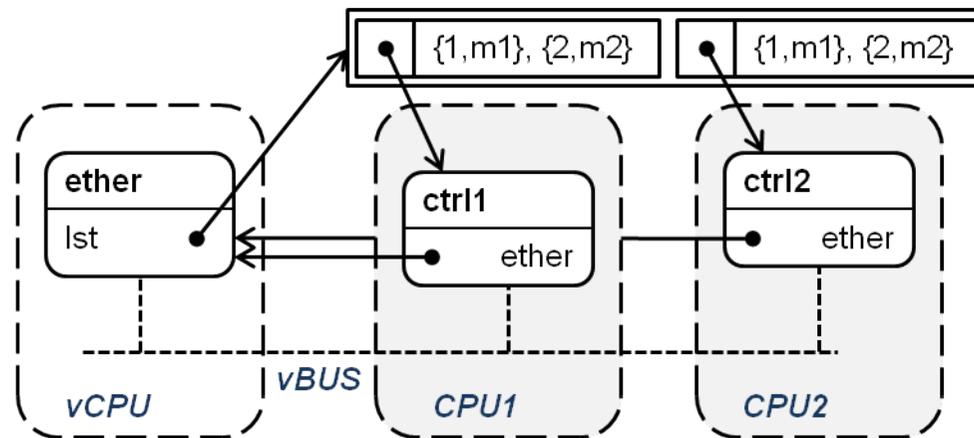
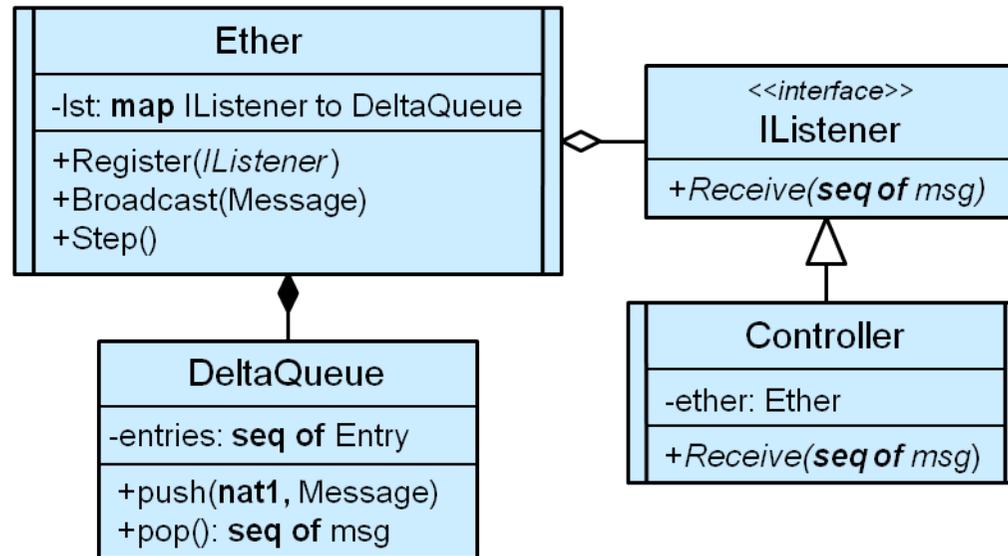
[AIS77] Christopher Alexander, Sara Ishikawa, Murray Silverstein. *A Pattern Language: Towns, Buildings, Construction*. Oxford University Press, 1977.

Ether Pattern (1)

- Model realistic communications
- Explicit model of an ***ether***
 - a medium through which data must travel
- Ether can lose, duplicate, corrupt messages
 - can be tailored to offer different guarantees representing different media



Ether Pattern (2)

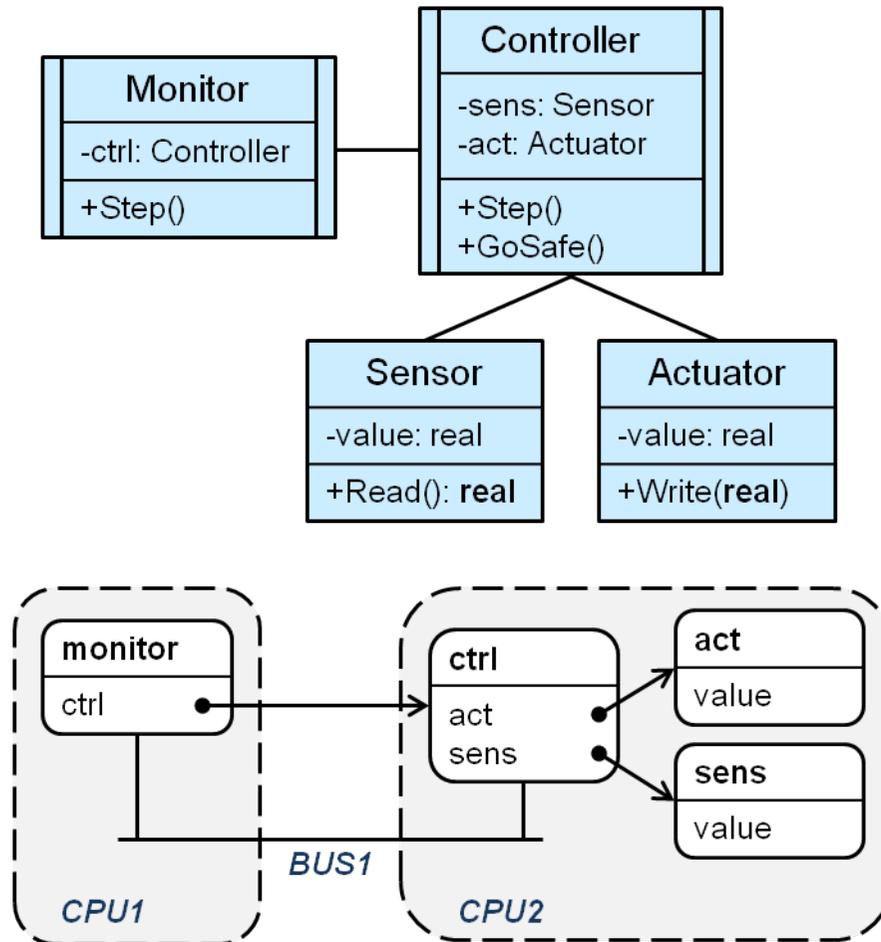


Monitor Pattern (1)

- Small, verifiable monitor that runs as a separate process
- Observes actions of the controller or other components
- Can intervene in undesirable or unsafe situations
- [See also **kernel pattern**]

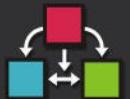


Monitor Pattern (2)



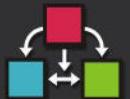
```

class Monitor
instance variables
  ctrl: Controller
operations
  private Step: () ==> ()
  Step() ==
    if not safe(ctrl) then ctrl.GoSafe()
  post safe(ctrl)
functions
  private safe: Controller -> bool
  notsafe(ctrl) == ...
thread
  periodic(1E5,1,0,0)(Step); -- 10kHz
end Monitor
  
```



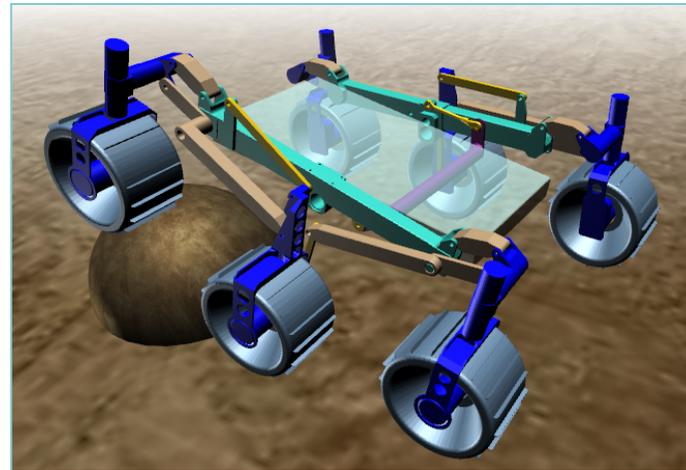
Conclusions

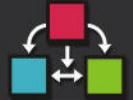
- Design of resilient cyber-physical systems through:
 - the collaborative creation of heterogeneous co-models, and
 - their analysis by co-simulation
- Supported by guidelines, patterns and tools
- Small embedded systems examples



Future Work and Challenges

- From embedded systems to cyber-physical
 - increasing capability of the tool support, e.g. new scripting features, batch execution
- Simulation of multiple systems
 - Issues of abstraction, scale
- Wider range of human behaviours





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