

Performance of Zinder-Roper algorithm for unitary RCPSP with constant precedence latencies *

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Scheduling problems on multiprocessors systems with precedence constraints are among the most difficult problems, in particular for the design of good approximation algorithms. Until now, much work has been done considering a model with identical processors and unit execution time tasks subject to precedence relations. However, one major architectural feature on the modern microprocessors is the employment of multiple specialized and pipelined functional units. Each functional unit executes only a specific type of tasks, and it is pipelined, it can start a new task every time unit, although the whole computation of a task takes a time which might be greater than one.

In order to model such realistic situations, we define the unitary RCPSP. In the three-field notation (see for example [2]), the above problem, with k types of processors is denoted by

$$\Sigma^k P|prec, \delta_{ij}, p_i = 1|L_{max}$$

where the terms $prec$ and δ_{ij} indicate the presence of precedence latencies, associating with each precedence constraint a constant amount of time which must elapse between the completion and start times of the corresponding tasks. This instance has a set of n tasks \mathcal{T} . Each task $i \in \mathcal{T}$ requires one unit of processor's time and it has a due-date d_i and a boolean type vector $\{b_r\}_{1 \leq r \leq k}$ where $b_r = 1$ when i is processed on processor of type r .

A schedule σ assigns a completion time $C_i(\sigma)$ to each task i . The maximum lateness of σ is defined as follows

$$L_{max}(\sigma) = \max_{i \in \mathcal{T}} C_i^\sigma - d_i$$

A well-studied special case is the makespan problem on identical processors. In fact, if all due dates are equal to zero and all tasks and all processors have the same type, then the maximum lateness problem becomes the makespan problem on identical processors

$$P|prec, \delta_{ij}, p_i = 1|C_{max}$$

with the criterion $C_{max}(\sigma) = \max_{i \in \mathcal{T}} C_i(\sigma)$.

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It is well known that even $P|prec, p_j = 1|C_{max}$ is NP-hard in the strong sense [5], [4]. Moreover, as has been shown in [6], the $P|prec, p_j = 1|C_{max}$ problem remains NP-hard in the strong sense even if the partially ordered set of tasks is a bipartite graph. These NP-hardness results boost the interest in the worst-case performance of various approximation algorithms for this problem [2],[1], [6], [7].

When due-dates are involved, and maximum lateness is optimized, the first version of Garey-Johnson algorithm solves optimally the problem when $m = 2$, $\delta = 0$. In [3], the generalization of this algorithm to unitary RCPSP with constant latency δ leads to the following worst case performance :

$$L_{max}^{GJ} \leq \left(k + 1 - \frac{\alpha(m_x)}{\delta + 1}\right) L_{max}^{opt} + \left(k - \frac{\alpha(m_x)}{\delta + 1}\right) d_{max} - \frac{\alpha(m_x)}{\delta + 1}$$

with $d_{max} = \max_{i \in \mathcal{T}} d_i$, $m_x = \max_{1 \leq r \leq k} m_r$ and

$$\alpha(m_x) = \begin{cases} \frac{2}{m_x} & \text{for even } m_x \\ \frac{2}{m_x+1} & \text{for odd } m_x \end{cases} .$$

The best known performance guarantee for the L_{max} on parallel processors without latencies is given by [8] :

$$L_{max}^{ZR} \leq \left(2 - \frac{2}{m}\right) L_{max}^{opt} + \left(1 - \frac{2}{m}\right) d_{max}$$

In this presentation, we study the Zinder-Roper extension for the maximum lateness minimization on unitary RCPSP with precedence latencies and we prove that the performance guarantee obtained,

$$L_{max}^{ZR} \leq \left(k + 1 - \frac{2}{m_x(\delta + 1)}\right) L_{max}^{opt} + \left(k - \frac{2}{m_x(\delta + 1)}\right) d_{max} - 1 + \frac{3}{m_x(\delta + 1)}$$

with $\delta = \max_{(i,j) \in G} \delta_{ij}$, outperforms the bounds for general list schedules, and coincides with the Zinder-Roper bound for parallel processors without latencies.

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